

Convex Optimization

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Lecture 9:

Matrix Inequalities and
Semi-Definite Programming

Reading: Boyd and Vandenberghe Sections 2.2.5, 4.6.2, 4.6.3, 5.9.1-5.9.3

Matrix Inequalities (Semi Definite Constraints)

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq 0 \\ & h_i(x) = 0 \end{array}$$

$$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \text{ convex}$$

$$f_i: \mathbb{R}^n \rightarrow S^{k_i} \subset \mathbb{R}^{k_i \times k_i} \text{ **matrix-convex** :}$$

$$f_i(\theta x + (1 - \theta)x') \preceq \theta f_i(x) + (1 - \theta)f_i(x')$$

$$h_i: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear (or } \rightarrow S^k, \text{ doesn't matter much)}$$

Sometimes convenient to represent $x \in S^n$: doesn't matter much, its just a vector space of dimensionality $n(n + 1)/2$

Semi-Definite Programming (SDP): f_0, f_i **linear**

Example: Closest Legal Covariance

$$\begin{array}{ll} \min_{A \in S^n} & \sum_{ij} |A_{ij} - \tilde{A}_{ij}| \\ \text{s. t.} & A \succcurlyeq 0 \end{array}$$

Example: Fastest Mixing Markov Chain

$$\begin{array}{ll}
 \min_{\substack{P \in S^n \\ t \in \mathbb{R}}} & t \\
 & \forall_i \sum_j P_{ij} = 1 \quad (P\mathbf{1} = \mathbf{1}) \\
 & \forall_{ij} P_{ij} \geq 0 \quad (P \geq 0) \\
 & \forall_{ij \notin E} P_{ij} = 0 \\
 & \forall_{ij} P_{ij} = P_{ji} \quad (P^\top = P) \\
 & -tI \preceq P - \frac{1}{n} \mathbf{1}\mathbf{1}^\top \preceq tI
 \end{array}$$

- Given undirected graph $G(V, E)$ on $V = \{1, \dots, n\}$ we want to construct random walk $X(t)$ on graph with symmetric transitions

$$P(X(t+1) = j | X(t) = i) = P_{ij} = P_{ji}$$

that minimizes the “mixing time”, i.e. the time by which $X(t)$ is approximately uniform and independent of $X(0)$.

- Eigenvalues of P : $1 = \lambda_1 \geq \lambda_2 \geq \lambda_2 \geq \dots \geq \lambda_n \geq -1$

$P\mathbf{1} = \mathbf{1}$, hence $\mathbf{1}$ is e.vec. with e.val. 1

- Claim: mixing time $\propto -\frac{1}{\log(\max(\lambda_2, -\lambda_n))}$
 $\rightarrow$ we want to minimize $\max(\lambda_2, -\lambda_n)$

Example: Max-Cut Relaxation

- Given weighted undirected graph $G([n], E)$ on nodes $[n] = \{1, \dots, n\}$ with weights $w_{ij} > 0$, find maximal cut, i.e. partition $[n] = A \cup B$ maximizing:

$$\sum_{i \in A, j \in B} w_{ij}$$

- A quadratic integer program:

$$\begin{array}{ll} \min_{x_i \in \mathbb{R}} & -\sum_{ij \in E} w_{ij} \left(\frac{(1 - x_i x_j)}{2} \right) \\ \text{s. t.} & x_i \in \pm 1 \end{array}$$

- Relaxing to vector “indicators”:

$$\begin{array}{ll} \min_{v_i \in \mathbb{R}^n} & -\sum_{ij \in E} w_{ij} \left(\frac{(1 - \langle v_i, v_j \rangle)}{2} \right) \\ \text{s. t.} & \|v_i\| = 1 \end{array}$$

- Equivalent program, $K = VV^T$:

$$\begin{array}{ll} \min_{K \in S^n} & -\sum_{ij \in E} w_{ij} \left(\frac{(1 - K_{ij})}{2} \right) \\ \text{s. t.} & K \succeq 0 \\ & K_{ii} = 1 \end{array}$$

- Randomized rounding: $\tilde{x}_i = \text{sign}(\langle u, v_i^* \rangle)$ for random vector u
- Theorem (Goemans Williamson '94): $\mathbb{E}_u[f_0(\tilde{x})] \leq 0.87 f_0(V^*) \leq 0.87 f_0(x^*)$

Duality with Matrix Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq 0 \quad \lambda_i \in S^{k_i} \\ & h_i(x) = 0 \quad v_i \in \mathbb{R} \end{array}$$

$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ convex, $f_i: \mathbb{R}^n \rightarrow S^{k_i}$ matrix convex, $h_j: \mathbb{R}^n \rightarrow \mathbb{R}$ linear

$$L(x, (\lambda, v)) = f_0(x) + \sum_{i=1}^m \langle \lambda_i, f_i(x) \rangle + \sum_{j=1}^p v_j h_j(x)$$

$$p^* = \inf_x \sup_{\lambda_i \succeq 0, v} L(x, (\lambda, v))$$

$f_i(x) \preceq 0 \rightarrow$ for $\lambda_i \succeq 0$ we have $\langle f_i(x), \lambda_i \rangle \leq 0$ and $\sup = 0$

$f_i(x)$ has a eigenvalue $s > 0$ with eigenvector v

$\rightarrow$ for $\lambda_i = t v v^T$ we have $\langle f_i(x), \lambda_i \rangle = t s \xrightarrow{t \rightarrow \infty} \infty$

Duality with Matrix Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq 0 \quad \lambda_i \in S^{k_i} \\ & h_i(x) = 0 \quad v_i \in \mathbb{R} \end{array}$$

$$\begin{array}{ll} \max_{\lambda_i \in S^{k_i}, v \in \mathbb{R}^p} & g(\lambda, v) \\ \text{s. t.} & \lambda_i \succeq 0 \end{array}$$

$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ convex, $f_i: \mathbb{R}^n \rightarrow S^{k_i}$ matrix convex, $h_j: \mathbb{R}^n \rightarrow \mathbb{R}$ linear

$$L(x, (\lambda, v)) = f_0(x) + \sum_{i=1}^m \langle \lambda_i, f_i(x) \rangle + \sum_{j=1}^p v_j h_j(x)$$

$$p^* = \inf_x \sup_{\lambda_i \succeq 0, v} L(x, (\lambda, v)) \geq \sup_{\lambda_i \succeq 0, v} \inf_x L(x, (\lambda, v)) = d^*$$

$$g(\lambda, v) = \inf_x L(x, (\lambda, v))$$

Slater ($\exists$ feasible x s.t. $f_i(x) \prec 0$) $\Rightarrow$ Strong duality

Complementary Slackness

- With strong duality, for optimal $x^*, (\lambda^*, v^*)$:

$$\begin{aligned}
 f_0(x^*) &= g(\lambda^*, v^*) = \inf_x L(x, (\lambda^*, v^*)) \leq L(x^*, (\lambda^*, v^*)) \\
 &= f_0(x^*) + \underbrace{\sum_i \langle \underbrace{\lambda_i^*}_{\text{green } 0}, \underbrace{f_i(x^*)}_{\text{blue } 0} \rangle}_{\text{IA } 0} + \sum_i \cancel{v_i^* h_i(x^*)}
 \end{aligned}$$

→ $\langle \lambda_i^*, f_i(x^*) \rangle = 0$

- Does this mean that $\lambda_i^* = 0$ or $f_i(x^*) = 0$?

- No: e.g. $\lambda_i^* = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, f_i(x^*) = \begin{bmatrix} 0 & 0 \\ 0 & -1 \end{bmatrix}$

- But: since $0 = \text{tr}(\lambda_i^{*\top} f_i(x^*))$ and $\lambda_i^{*\top} f_i(x^*) \preceq 0$, we must have:
 $\lambda_i^{*\top} f_i(x^*) = 0 \in S^{k_i}$

- Also: $x^* = \arg \min L(x, (\lambda^*, v^*))$

Optimality Condition (assuming Strong Duality)

		<u>KKT Conditions</u>
x^* optimal for (P)	$\longrightarrow$	$f_i(x^*) \leq 0 \quad \forall i=1\dots m$
λ^*, v^* optimal for (D)	$\longleftarrow$	$h_j(x^*) = 0 \quad \forall j=1\dots p$
		$\lambda_i^* \geq 0 \quad \forall i=1\dots m$
		$\nabla_x L(x^*, (\lambda^*, v^*)) = 0$
		or $0 \in \partial_x L(x^*, (\lambda^*, v^*))$
		$\langle \lambda_i^*, f_i(x^*) \rangle = 0 \quad \forall i=1\dots m$

x^* optimal for (P) $\Leftrightarrow \exists \lambda^*, v^*$ s.t. x^*, λ^*, v^* satisfy KKT

Matrix Completion

low norm

V

U

	-1		-1			+1				+1	
	+1		+1				?		-1		-1
			-1		+1		+1				
+1			?			+1		-1		?	
		+1		-1	-1				+1		
			-1				-1	?			+1
	-1					+1		+1		+1	
		-1		?	+1		?		+1		
	+1		+1		-1		+1		-1		-1
	+1				-1			-1		+1	
	+1			+1	-1			+1			
		-1				-1	?				+1
-1	?		-1		-1						
		+1			-1	?		+1		+1	
	-1		-1		-1	+1		+1		+1	
-1		-1			+1				+1	?	

Given partial observations Y_{ij} for $(i, j) \in S$, reconstruct factors U, V s.t.

$$Y_{ij} \langle u_i, v_j \rangle \geq 1$$

Matrix Completion

$$\begin{array}{ll} \min_{u_i, v_j \in \mathbb{R}^k} & \frac{1}{2} \left(\sum_{i=1}^n \|u_i\|^2 + \sum_{j=1}^m \|v_j\|^2 \right) \\ \text{s. t.} & \forall_{ij \in S} Y_{ij} \langle u_i, v_j \rangle \geq 1 \end{array}$$

- If $k \geq n + m$, can express as:

$$\begin{array}{ll} \min_{\substack{A \in S^n, B \in S^m \\ X \in \mathbb{R}^{n \times m}}} & \frac{1}{2} (\text{tr}(A) + \text{tr}(B)) \\ \text{s. t.} & \begin{array}{c} U \\ V \end{array}^\top \begin{bmatrix} A & X \\ X' & B \end{bmatrix} \succcurlyeq 0 \\ & \forall_{ij \in S} Y_{ij} X_{ij} \geq 1 \end{array}$$

- $(n + m)^2$ variables
- $(n + m) \times (n + m)$ matrix inequality + $|S|$ scalar inequalities

Dual?

Dual of Matrix Completion

$$\begin{aligned} \min_{\substack{A \in \mathbb{S}^n, B \in \mathbb{S}^m \\ X \in \mathbb{R}^{n \times m}}} \quad & \frac{1}{2} (\text{tr}(A) + \text{tr}(B)) \\ \text{s.t.} \quad & \begin{bmatrix} A & X \\ X' & B \end{bmatrix} \succeq 0 \\ & \forall_{ij \in S} Y_{ij} X_{ij} \geq 1 \end{aligned}$$

$$\begin{bmatrix} \lambda_A & \lambda_X \\ \lambda_X^\top & \lambda_B \end{bmatrix}$$

α_{ij}

$$\max_{\alpha \in \mathbb{R}^S} \sum_{ij \in S} \alpha_{ij}$$

$$\text{s.t. } \alpha \geq 0$$

$$2\lambda = \begin{bmatrix} I_n & Q(\alpha) \\ Q(\alpha)^\top & I_m \end{bmatrix} \succeq 0$$

$$Q_{ij} = Y_{ij} \alpha_{ij} \text{ or } Q_{ij} = 0 \text{ if } ij \notin S$$

$$\|Q(\alpha)\|_2 \leq 1$$

$$\begin{aligned} L((X, A, B), (\lambda, \alpha)) &= \frac{1}{2} (\text{tr} A + \text{tr} B) - \left\langle \begin{bmatrix} \lambda_A & \lambda_X \\ \lambda_X^\top & \lambda_B \end{bmatrix}, \begin{bmatrix} A & X \\ X' & B \end{bmatrix} \right\rangle + \sum_{ij \in S} \alpha_{ij} (1 - Y_{ij} X_{ij}) \\ &= -2 \langle \lambda_X, X \rangle - \sum_{ij \in S} \alpha_{ij} Y_{ij} X_{ij} + \underbrace{\langle \frac{1}{2} I_n - \lambda_A, A \rangle}_{\text{tr} A = \langle I, A \rangle} + \underbrace{\langle \frac{1}{2} I_m - \lambda_B, B \rangle}_{\text{tr} B = \langle I, B \rangle} + \sum_{ij \in S} \alpha_{ij} \end{aligned}$$

$$g(\lambda, \alpha) = \inf_{X, A, B} L((X, A, B), (\lambda, \alpha)) = \sum \alpha_{ij}$$

$$\text{s.t. } \lambda_A = \frac{1}{2} I_n, \lambda_B = \frac{1}{2} I_m \text{ and } (\lambda_X)_{ij} = \begin{cases} 0 & ij \notin S \\ -\frac{1}{2} Y_{ij} \alpha_{ij} & ij \in S \end{cases}$$