

Convex Optimization

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Lecture 10:

Generalized Inequalities

Multiple Objectives

Reading: Boyd and Vandenberghe Sections 2.4, 2.6, 3.6, 4.6—4.7, 5.9

Matrix Inequalities (Semi Definite Constraints)

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq 0 \\ & h_i(x) = 0 \end{array}$$

$$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \text{ convex}$$

$$f_i: \mathbb{R}^n \rightarrow S^{k_i} \subset \mathbb{R}^{k_i \times k_i} \text{ **matrix-convex** :}$$

$$f_i(\theta x + (1 - \theta)x') \preceq \theta f_i(x) + (1 - \theta)f_i(x')$$

$$h_i: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear (or } \rightarrow S^k, \text{ doesn't matter much)}$$

Sometimes convenient to represent $x \in S^n$: doesn't matter much, its just a vector space of dimensionality $n(n + 1)/2$

Semi-Definite Programming (SDP): f_0, f_i **linear**

Duality with Matrix Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq 0 \quad \lambda_i \in S^{k_i} \\ & h_i(x) = 0 \quad v_i \in \mathbb{R} \end{array}$$

$$\begin{array}{ll} \max_{\lambda_i \in S^{k_i}, v \in \mathbb{R}^p} & g(\lambda, v) \\ \text{s. t.} & \lambda_i \succeq 0 \end{array}$$

$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ convex, $f_i: \mathbb{R}^n \rightarrow S^{k_i}$ matrix convex, $h_j: \mathbb{R}^n \rightarrow \mathbb{R}$ linear

$$L(x, (\lambda, v)) = f_0(x) + \sum_{i=1}^m \langle \lambda_i, f_i(x) \rangle + \sum_{j=1}^p v_j h_j(x)$$

$$p^* = \inf_x \sup_{\lambda_i \succeq 0, v} L(x, (\lambda, v)) \geq \sup_{\lambda_i \succeq 0, v} \inf_x L(x, (\lambda, v)) = d^*$$

$$g(\lambda, v) = \inf_x L(x, (\lambda, v))$$

Slater ($\exists$ feasible x s.t. $f_i(x) \prec 0$) $\Rightarrow$ Strong duality

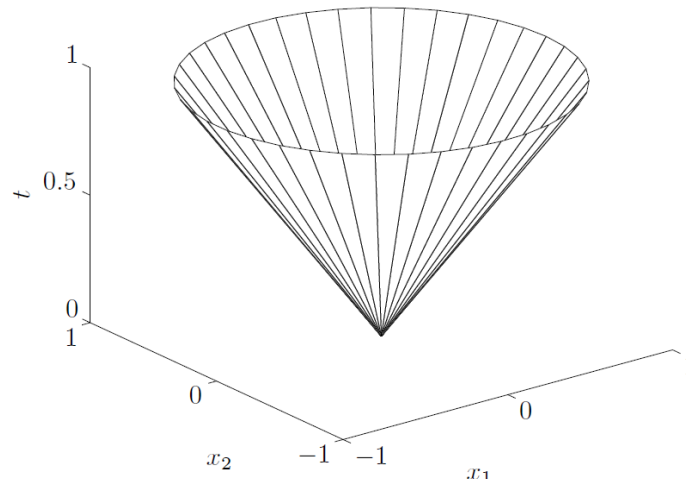
Optimality Condition (assuming Strong Duality)

		<u>KKT Conditions</u>
x^* optimal for (P)		$f_i(x^*) \leq 0 \quad \forall i=1\dots m$
λ^*, v^* optimal for (D)		$h_j(x^*) = 0 \quad \forall j=1\dots p$
		$\lambda_i^* \geq 0 \quad \forall i=1\dots m$
		$\nabla_x L(x^*, (\lambda^*, v^*)) = 0$
		or $0 \in \partial_x L(x^*, (\lambda^*, v^*))$
		$\langle \lambda_i^*, f_i(x^*) \rangle = 0 \quad \forall i=1\dots m$

x^* optimal for (P) $\Leftrightarrow \exists \lambda^*, v^*$ s.t. x^*, λ^*, v^* satisfy KKT

Generalized Inequalities

- More generally: $f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i}$ with the constraint $-f_i(x) \in K_i$ where $K_i \subset \mathbb{R}^{k_i}$ is a **closed pointed convex cone** with non-empty interior (“proper cone”)
 - Cone: $x \in K, \theta > 0 \rightarrow \theta x \in K$
 - Pointed: $x \in K, x \neq 0 \rightarrow -x \notin K$
- Examples:
 - $K = \mathbb{R}_+$: scalar non-negativity constraints
 - $K = \mathbb{R}_+^k$ (positive orthant): elementwise non-negativity
 - $K = S_+^k = \{X \in S^k | X \succcurlyeq 0\}$: semi-definite constraint
 - $K = \{ [x \ t], x \in \mathbb{R}^{k-1}, t \in \mathbb{R} \mid \|x\| \leq t \}$ (norm cone)

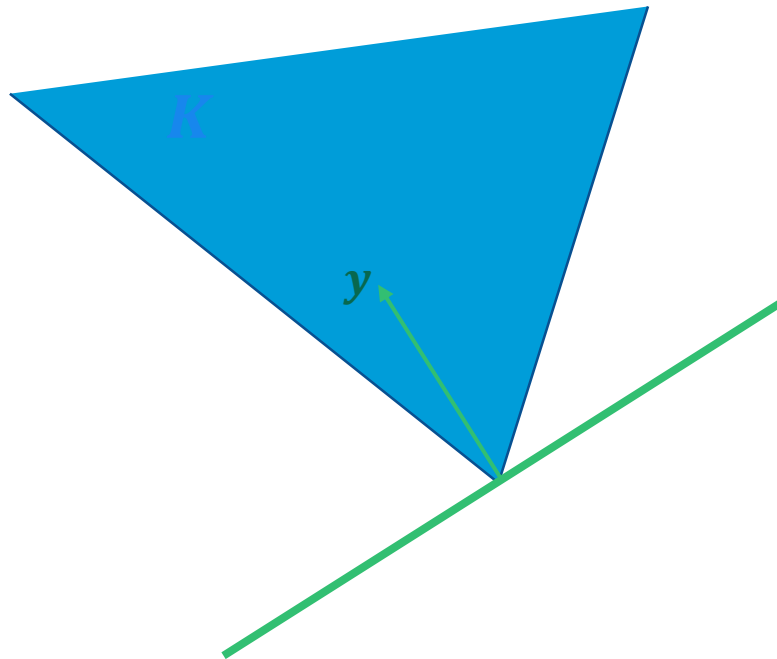


Generalized Inequalities

- More generally: $f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i}$ with the constraint $-f_i(x) \in K_i$ where $K_i \subset \mathbb{R}^{k_i}$ is a **closed pointed convex cone** with non-empty interior (“proper cone”)
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- Examples:
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 - $K = S_+^k = \{X \in S^k | X \succcurlyeq 0\}$: semi-definite constraint
 - $K = \{ [x \ t], x \in \mathbb{R}^{k-1}, t \in \mathbb{R} \mid \|x\| \leq t \}$ (norm cone)
- Notation: $x \preccurlyeq_K y$ means $y - x \in K$
 - Constraint: $f_i(x) \preccurlyeq_K 0$
- K -convexity: $f(\theta x + (1 - \theta)x') \preccurlyeq_K \theta f(x) + (1 - \theta)f(x')$

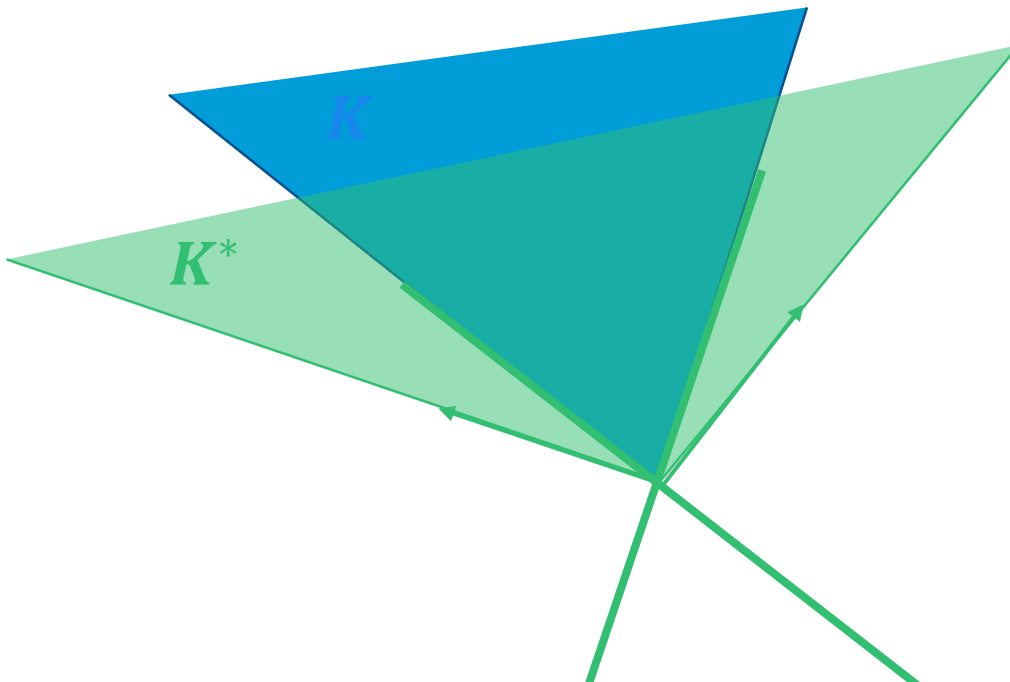
Dual Cone

$$K^* = \{ \textcolor{teal}{y} \in (\mathbb{R}^k)^* \mid \forall_{(\textcolor{blue}{x} \in K)} \langle \textcolor{teal}{y}, \textcolor{blue}{x} \rangle \geq 0 \}$$



Dual Cone

$$K^* = \{ \textcolor{teal}{y} \in (\mathbb{R}^k)^* \mid \forall_{(\textcolor{blue}{x} \in K)} \langle \textcolor{teal}{y}, \textcolor{blue}{x} \rangle \geq 0 \}$$



Dual Cone

$$K^* = \{ \textcolor{teal}{y} \in (\mathbb{R}^k)^* \mid \forall_{(\textcolor{blue}{x} \in K)} \langle \textcolor{teal}{y}, \textcolor{blue}{x} \rangle \geq 0 \}$$

- $(\mathbb{R}_+^k)^* = \mathbb{R}_+^k$
- $(S_+^k)^* = S_+^k$
- $\{ [x \ t], x \in \mathbb{R}^{k-1}, t \in \mathbb{R} \mid \|x\| \leq t \}^*$
 $= \{ [y \ s], y \in \mathbb{R}^{k-1}, s \in \mathbb{R} \mid \|y\|_* \leq s \}$

Generalized Inequality Constraints

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\} \text{ convex}$$

$$f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i} \text{ } K_i\text{-convex}$$

$$h_j: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear}$$

Can always combined to single conic constraint:

$$\tilde{f}(x) = [f_1(x); f_2(x); \dots; f_m(x)] \preceq_K 0$$

$$\tilde{f}(x): \mathbb{R}^n \rightarrow \mathbb{R}^k \quad k = \sum_i k_i$$

$$K = K_1 \times K_2 \times \dots \times K_m$$

Cone Programs: Generalized Linear Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & c^\top x \\ \text{s.t.} & Gx \preceq_K h \\ & Ax = b \end{array}$$

Inequality form:

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & c^\top x \\ \text{s.t.} & \tilde{G}x \preceq_{\tilde{K}} \tilde{h} \end{array}$$

$$\begin{array}{l} Gx \preceq_K h \\ Ax \preceq_K b \\ (-A)x \preceq_K -b \end{array}$$

Standard form:

$$\begin{array}{ll} \min_{z \in \mathbb{R}^{\tilde{n}}} & c^\top z \\ \text{s.t.} & z \succeq_{\tilde{K}} 0 \\ & \tilde{A}z = \tilde{b} \end{array}$$

$$\begin{array}{l} z = [x_+; x_-; t] \\ t = h - G(x_+ - x_-) \\ A(x_+ - x_-) = b \end{array}$$

Linear Programming (LP)

$$\begin{array}{ll}\min_{x \in \mathbb{R}^n} & c^\top x \\ \text{s.t.} & Gx \leq h \\ & Ax = b\end{array}$$

Quadratic Programming (QP)

$$\begin{array}{ll}\min_{x \in \mathbb{R}^n} & x^\top Px + q^\top x \\ \text{s.t.} & Gx \leq h \\ & Ax = b\end{array}$$

Second Order Cone Programming (SOCP)

$$\begin{array}{ll}\min_{x \in \mathbb{R}^n} & c^\top x \\ \text{s.t.} & \|G_i x - h_i\|_2 \leq q_i^\top x + r_i \\ & i = 1..m \\ & Ax = b\end{array}$$

Quadratically Constrained Quadratic Programming (QCQP)

$$\begin{array}{ll}\min_{x \in \mathbb{R}^n} & x^\top P_0 x + q_0^\top x \\ \text{s.t.} & x^\top P_i x + q_i^\top x \leq r_i \\ & i = 1..m \\ & Ax = b\end{array}$$

Semidefinite Programming (SDP)

$$\begin{array}{ll}\min_{x \in \mathbb{R}^n} & c^\top x \\ \text{s.t.} & Gx \preceq h \\ & Ax = b\end{array}$$

Dual Cones and Generalized Inequalities

$$K^* = \{y \in (\mathbb{R}^k)^* \mid \forall_{x \in K} \langle y, x \rangle \geq 0\}$$

- For a proper cone (pointed cone with non-empty interior): $K^{**} = K$, i.e.

$$K^{**} = \{x \in \mathbb{R}^k \mid \forall_{y \in K^*} \langle y, x \rangle \geq 0\} = K$$

- Claim:

$$f_i(x) \preceq_K 0 \Leftrightarrow \overbrace{\sup_{\lambda \succ_{K^*} 0} \langle \lambda, f_i(x) \rangle}^{\text{must be 0 or } \infty} < \infty$$

- Proof of $\Rightarrow$: $\langle \lambda, f_i(x) \rangle = -\langle \lambda, -f_i(x) \rangle \leq 0$
- Proof of $\Leftarrow$: $\forall_{\lambda \in K^*} \langle \lambda, -f_i(x) \rangle \geq 0 \Rightarrow -f_i(x) \in K^{**} = K$

Duality with Generalized Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$\begin{array}{ll} \max_{\lambda_i \in \mathbb{R}^{k_i}, v \in \mathbb{R}^p} & g(\lambda, v) \\ \text{s. t.} & \lambda_i \succeq_{K_i^*} 0 \end{array}$$

$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ convex, $f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i}$ K_i -convex, $h_j: \mathbb{R}^n \rightarrow \mathbb{R}$ linear

- Can write primal as:

$$p^* = \inf_x \sup_{\lambda_i \succeq_{K_i^*} 0, v} f_0(x) + \sum_{i=1}^m \langle \lambda_i, f_i(x) \rangle + \sum_{j=1}^p \langle v_j, h_j(x) \rangle$$

- Dual objective (as usual):

$$g(\lambda, v) = \inf_x L(x, (\lambda, v))$$

Duality with Generalized Inequalities

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$\begin{array}{ll} \max_{\lambda_i \in \mathbb{R}^{k_i}, v \in \mathbb{R}^p} & g(\lambda, v) \\ \text{s. t.} & \lambda_i \succeq_{K_i^*} 0 \end{array}$$

$f_0: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\}$ convex, $f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i}$ K_i -convex, $h_j: \mathbb{R}^n \rightarrow \mathbb{R}$ linear

KKT Conditions

x^* optimal for (P)

λ^*, v^* optimal for (D)



$$f_i(x^*) \preceq_{K_i} 0 \quad \forall i=1..m$$

$$h_j(x^*) = 0 \quad \forall j=1..p$$

$$\lambda_i^* \succeq_{K_i^*} 0 \quad \forall i=1..m$$

$$\nabla_x L(x^*, (\lambda^*, v^*)) = 0$$

$$\text{or } 0 \in \partial_x L(x^*, (\lambda^*, v^*))$$

$$\langle \lambda_i^*, f_i(x^*) \rangle = 0 \quad \forall i=1..m$$

Multi-Dimensional Objective

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s.t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$f_0: \mathbb{R}^n \rightarrow \mathbb{R}^k \cup \{\infty\} \text{ } K\text{-convex}$$

$$f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i} \text{ } K_i\text{-convex}, h_j: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear}$$

- Minimization is w.r.t. cone K : We prefer x over x' if $f_0(x) \preceq_K f_0(x')$
- Problem: might not be able to compare,
i.e. possible that $f_0(x) \not\preceq_K f_0(x')$ but also $f_0(x') \not\preceq_K f_0(x)$

Multi-Criteria Optimization

$$f_0(x) = [F_1(x) \ F_2(x) \ \dots F_k(x)] \in \mathbb{R}^k$$

- Optimization w.r.t. positive orthant, i.e. elementwise comparison
 $f_0(x) \preceq_K f_0(x') \equiv f_0(x) \leq f_0(x') \equiv \forall_i (F_i(x) \leq F_i(x'))$

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & F_1(x), F_2(x), \dots, F_k(x) \\ \text{s. t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$F_i: \mathbb{R}^n \rightarrow \mathbb{R} \cup \{\infty\} \text{ convex}$$

$$f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i} \text{ } K_i\text{-convex, } h_j: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear}$$

Examples

- Maximizing expected return and minimizing risk
 n stocks with means $\mu \in \mathbb{R}^n$ and covariance S

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & F_1(x) = -\langle \mu, x \rangle, \quad F_2(x) = x^\top S x \\ \text{s. t.} & x \geq 0 \\ & \sum_{i=1}^n x_i = 1 \end{array}$$

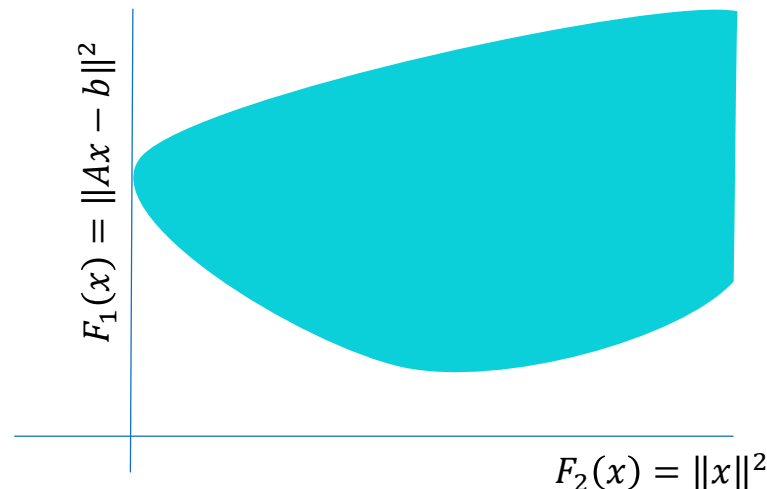
- Model fit and model complexity (regularization)

$$\min_{w \in \mathbb{R}^n} \quad F_1(w) = \|Aw - b\|_2^2, \quad F_2(w) = \|w\|_2^2$$

What is “Optimal”?

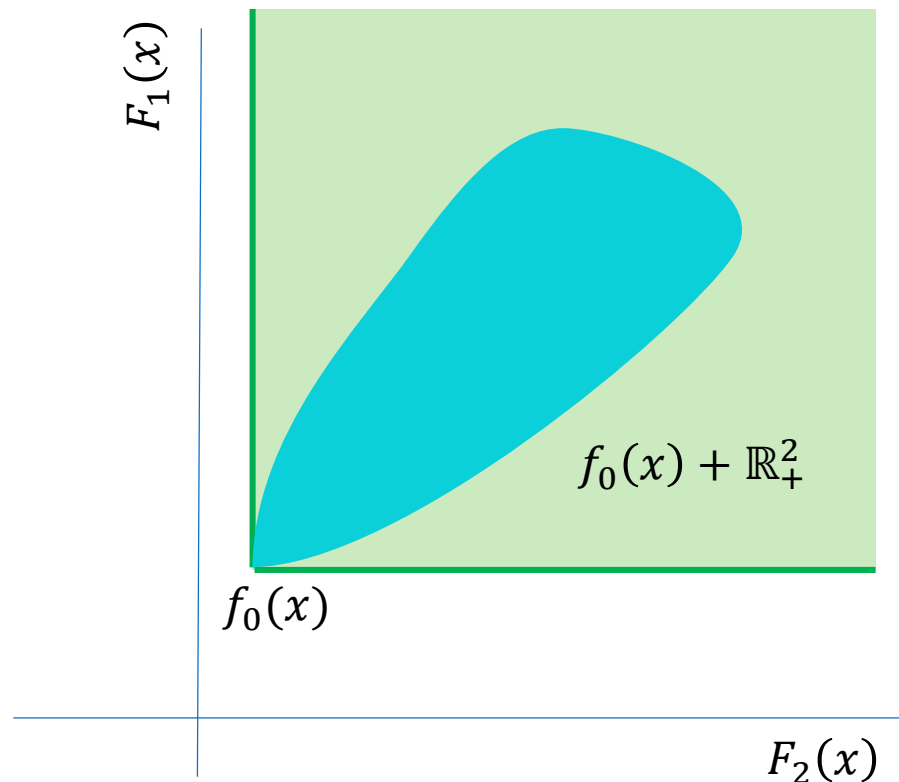
$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) = [F_1(x), F_2(x), \dots, F_k(x)] \\ \text{s. t.} & f_i(x) \leq 0 \\ & h_i(x) = 0 \end{array}$$

- Definition: A feasible x is **optimal** if $\forall$ feasible y , $f_0(x) \leq f_0(y)$
i.e. if $\forall$ feasible y , $\forall i$, $F_i(x) \leq F_i(y)$
- Set of attainable solutions: $\mathcal{O} = \{f_0(x) \mid x \text{ is feasible}\}$



When Does an Optimum Exist

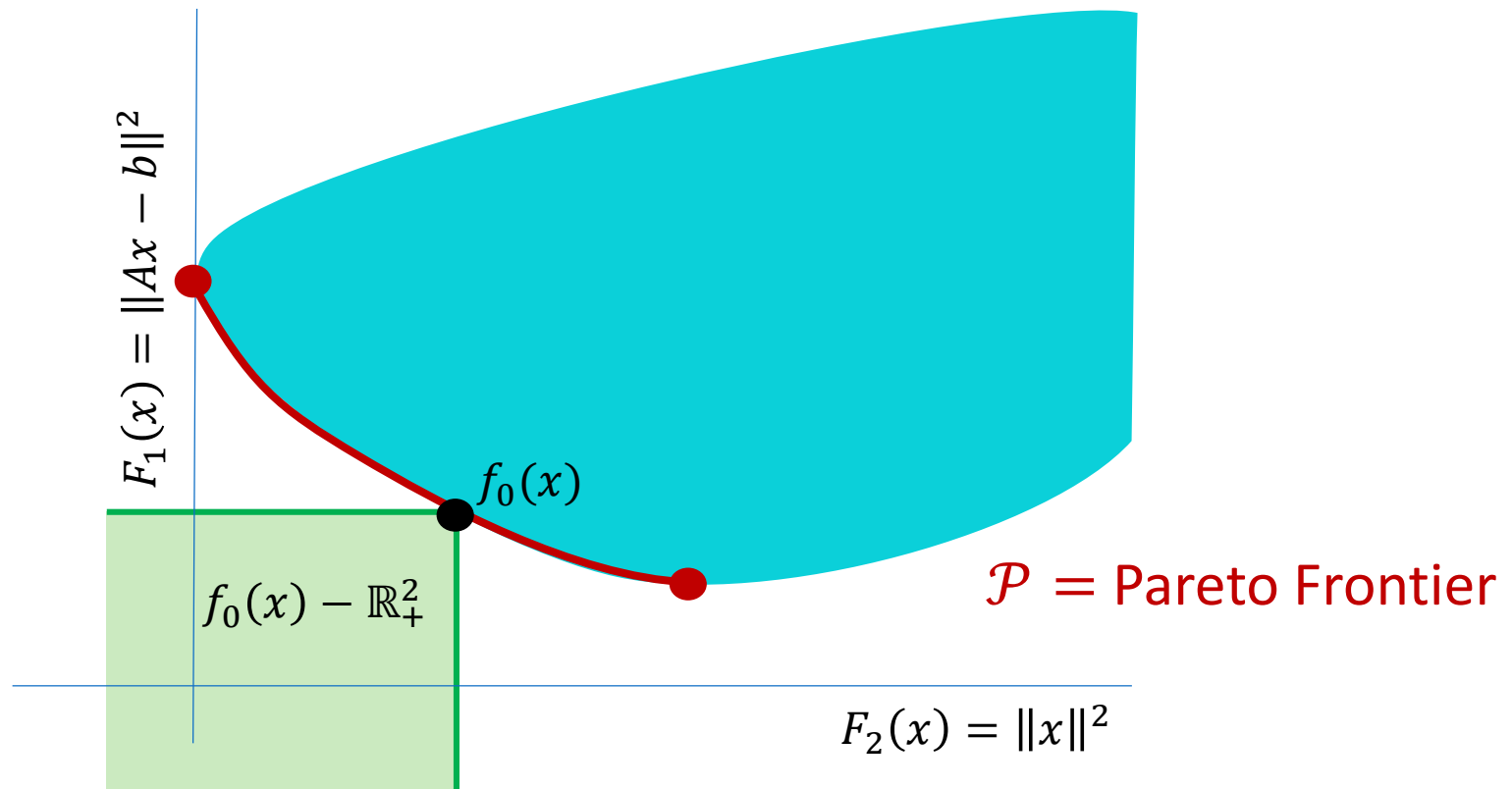
- Definition: A feasible x is **optimal** if $\forall$ feasible y , $f_0(x) \leq f_0(y)$
- Claim: A feasible x is optimal iff $\mathcal{O} \subseteq f_0(x) + \mathbb{R}_+^k$



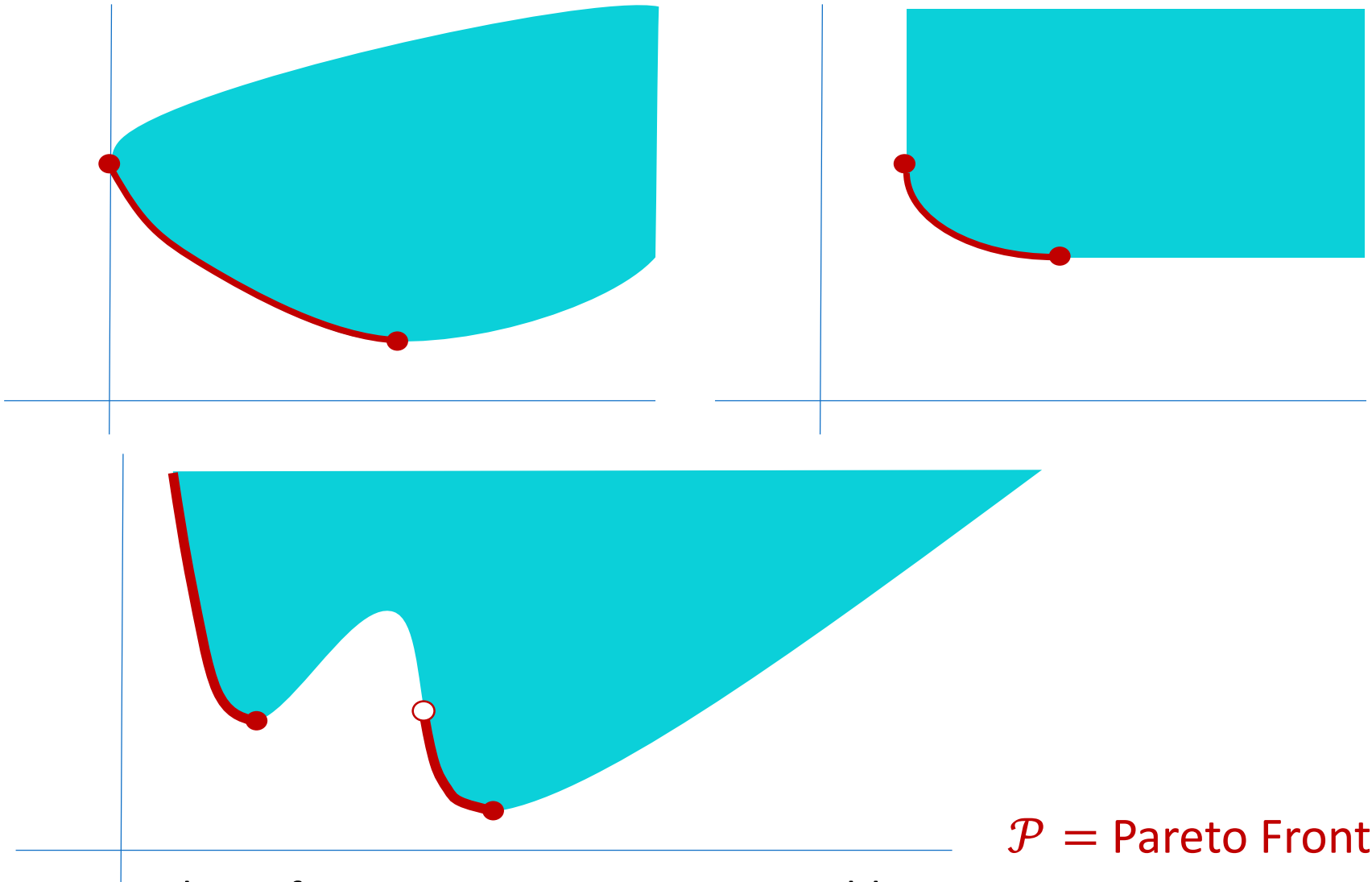
The Pareto Frontier

- Definition: A feasible x is **Pareto Optimal** iff

$$\forall \text{ feasible } y, f_0(y) \leq f_0(x) \rightarrow f_0(y) = f_0(x)$$
- Claim: A feasible x is Pareto Optimal iff $(f_0(x) - \mathbb{R}_+^k) \cap \mathcal{O} = \{f_0(x)\}$



Examples



$\mathcal{P}$ = Pareto Frontier

Claim: for a convex optimization problem,
 $\mathcal{O} + \mathbb{R}_+^n$ always convex and has same Pareto Frontier as $\mathcal{O}$

Scalarization

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) = [F_1(x), F_2(x), \dots, F_k(x)] \\ \text{s. t.} & f_i(x) \leq 0 \\ & h_i(x) = 0 \end{array}$$

- For $\lambda = (\lambda_1, \lambda_2, \dots, \lambda_k) \geq 0$, introduce the problem:

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & \langle \lambda, f_0(x) \rangle = \sum_{i=1}^k \lambda_i F_i(x) \\ \text{s. t.} & f_i(x) \leq 0 \\ & h_i(x) = 0 \end{array}$$

- Claim: for $\lambda > 0$, an optimum x_λ^* of the λ -problem is Pareto optimal

Proof: if $f_0(x) \leq f_0(x_\lambda^*)$ and better on at least one F_i , then $\langle \lambda, f_0(x) \rangle < \langle \lambda, f_0(x_\lambda^*) \rangle$

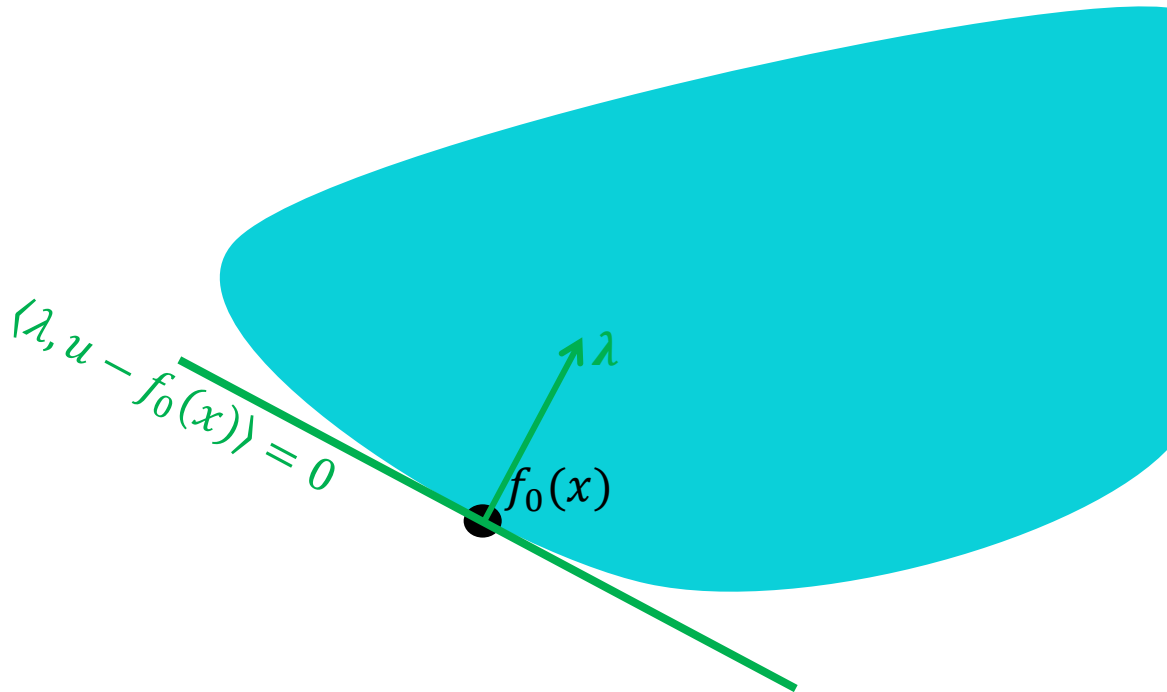
- Geometrically: $\forall_{feasible\ y} \langle \lambda, f_0(x_\lambda^*) \rangle \leq \langle \lambda, f_0(y) \rangle$

$$\Rightarrow \forall_{u \in \mathcal{O}} \langle \lambda, f_0(x_\lambda^*) \rangle \leq \langle \lambda, u \rangle$$

$$\Rightarrow \{u \mid \langle \lambda, u - f_0(x_\lambda^*) \rangle = 0\} \text{ is a supporting HP of } \mathcal{O}$$

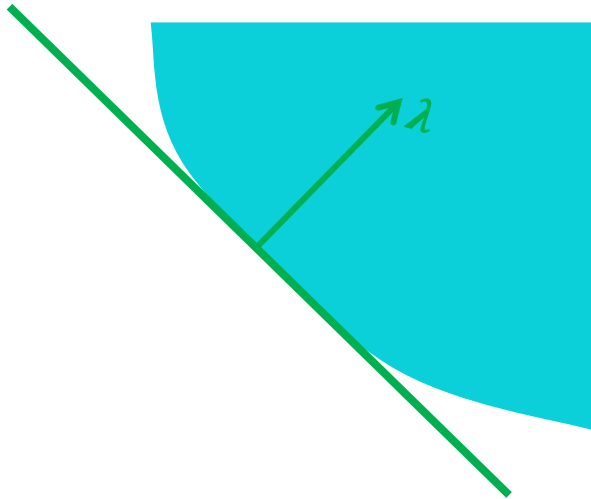
Scalarization

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & \langle \lambda, f_0(x) \rangle = \sum_{i=1}^k \lambda_i F_i(x) \\ \text{s. t.} & f_i(x) \leq 0 \\ & h_i(x) = 0 \end{array}$$



$$\{x_\lambda^* \text{ optimal for } \lambda - \text{problem} \mid \lambda > 0\} \subseteq \mathcal{P}$$

Scalarization



Multiple Pareto optimal x_λ^* for same λ

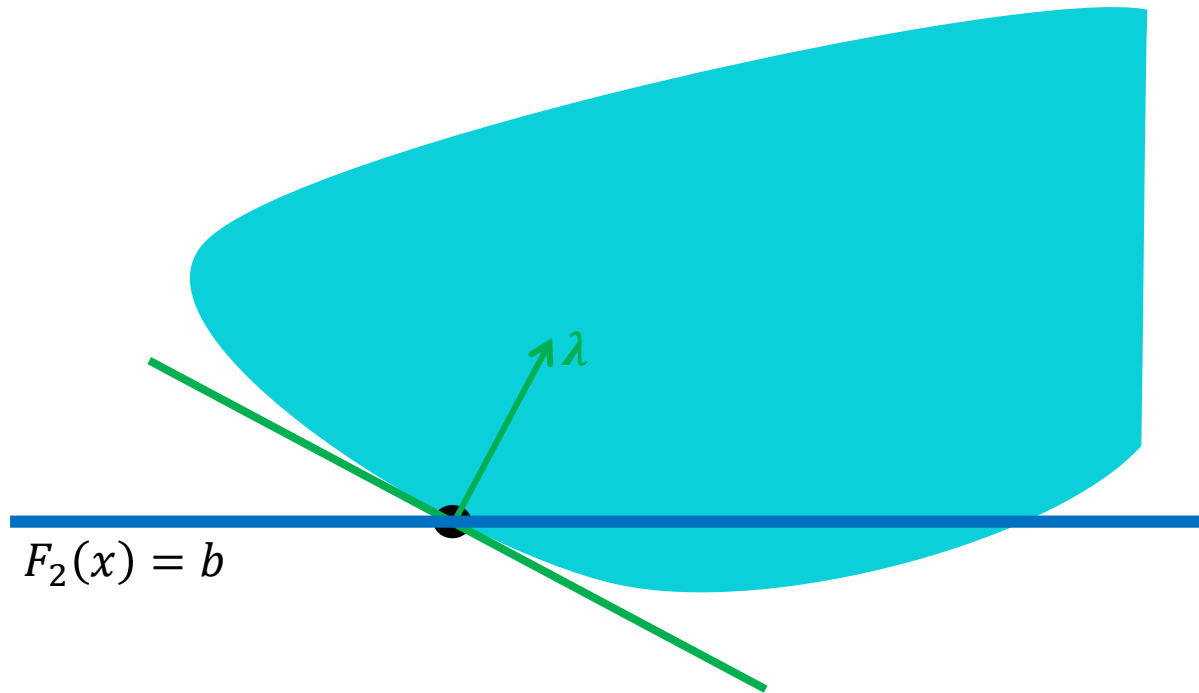


Not all x_λ^* for $\lambda = (1,0)$ and $\lambda = (0,1)$ are Pareto optimal

$$\begin{aligned} \{ x_\lambda^* \text{ optimal for } \lambda - \text{problem} \mid \lambda > 0 \} \\ \subseteq \mathcal{P} \subseteq \\ \{ x_\lambda^* \text{ optimal for } \lambda - \text{problem} \mid \lambda \geq 0 \} \end{aligned}$$

Criteria as Constraints

$$\min_{x \in \mathbb{R}^n} F_1(x), F_2(x)$$



$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & F_1(x) \\ \text{s. t.} & F_2(x) \leq b \end{array}$$

$$\min_{x \in \mathbb{R}^n} F_1(x) + \lambda F_2(x)$$

Optimization w.r.t. Cone K

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s. t.} & f_i(x) \preceq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

$$f_0: \mathbb{R}^n \rightarrow \mathbb{R}^k \cup \{\infty\} \text{ } K\text{-convex}$$

$$f_i: \mathbb{R}^n \rightarrow \mathbb{R}^{k_i} \text{ } K_i\text{-convex, } h_j: \mathbb{R}^n \rightarrow \mathbb{R} \text{ linear}$$

- Definition: A feasible x is **optimal** if $\forall$ feasible y , $f_0(x) \preceq_K f_0(y)$
- Claim: A feasible x is optimal iff $\mathcal{O} \subseteq f_0(x) + K$
- Definition: A feasible x is **Pareto Optimal** iff
$$\forall \text{ feasible } y, f_0(y) \preceq_K f_0(x) \rightarrow f_0(y) = f_0(x)$$
- Claim: A feasible x is Pareto Optimal iff $(f_0(x) - K) \cap \mathcal{O} = \{f_0(x)\}$

Scalarization for K -Optimization

$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & f_0(x) \\ \text{s.t.} & f_i(x) \preccurlyeq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

- For $\lambda \succcurlyeq_K 0$, introduce the problem:

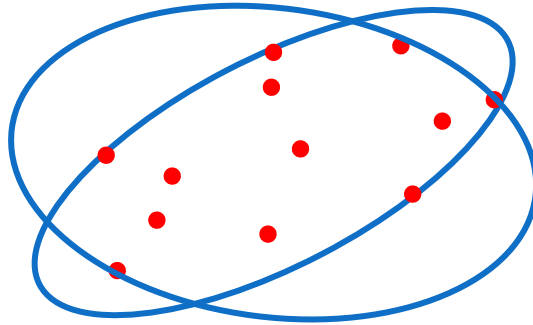
$$\begin{array}{ll} \min_{x \in \mathbb{R}^n} & \langle \lambda, f_0(x) \rangle \\ \text{s.t.} & f_i(x) \preccurlyeq_{K_i} 0 \\ & h_i(x) = 0 \end{array}$$

- Claim: for $\lambda \succ_K 0$, an optimum x_λ^* of the λ -problem is Pareto optimal

$$\lambda \in \text{interior}(K)$$

$$\begin{aligned} \{ x_\lambda^* \text{ optimal for } \lambda - \text{problem} \mid \lambda \succ_K 0 \} \\ \subseteq \mathcal{P} \subseteq \\ \{ x_\lambda^* \text{ optimal for } \lambda - \text{problem} \mid \lambda \succcurlyeq_K 0 \} \end{aligned}$$

Matrix Optimization: Example



- Find **minimal** encompassing ellipsoid of $a_1, a_2, \dots, a_m \in \mathbb{R}^n$ (i.e. encompassing ellipsoid that isn't a superset of any other encompassing ellipsoid)

$$\begin{array}{ll} \min_{X \in S^n} & (-X) \\ \text{s. t.} & a_i^\top X a_i \leq 1 \quad i = 1..m \end{array}$$

Optimization is w.r.t. the semi-definite cone (matrix inequality)